



Dr.M.G.R.
Educational and Research Institute
(DEEMED TO BE UNIVERSITY)
(An ISO Certified Institution)
University with Graded Autonomy Status
Maduravoyal, Chennai - 600 095



M.Tech – DESIGN ENGINEERING (FULL TIME)

**M.Tech – DESIGN ENGINEERING
(FULL TIME)**

**CURRICULUM
AND
SYLLABUS**

REGULATION: 2018

*M.Tech – DESIGN ENGINEERING (FULL TIME)
Regulation -2018*



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M.Tech – DESIGN ENGINEERING (FULL TIME)

DECLARATION

I, **Dr.M.Ganesan**, Head of Mechanical Engineering Department, hereby declare that this copy of the syllabus (M.Tech–Design Engineering Full time 2018 Regulation) is the final version which is being taught in the class and uploaded in our University website. I assure that the Syllabus available in our University website is verified and found correct. The Curriculum and Syllabi have been ratified by our Academic Council/Vice Chancellor.

Date:

Signature



M.Tech – DESIGN ENGINEERING (FULL TIME)
M.Tech – Design Engineering (Full Time)
Curriculum and Syllabus
2018 Regulation

I SEMESTER						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MMA18002	Applied Mathematics For Design Engineers	3	1	0	4
2	MME18D001	Concepts of Engineering Design	3	0	0	3
3	MME18D002	Computer Aided Design and Manufacturing	3	1	0	4
4	MME18D009	Advanced Strength of Materials	3	1	0	4
5	MME18D004	Design for Manufacturing and Assembly	3	1	0	4
6	MME18D005	Advanced Material Technology	3	0	0	3
7	MME18DL01	Design Analysis Lab	0	0	4	2
Total			18	4	4	24

II SEMESTER						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MME118D007	Advanced Mechanism Design	3	1	0	4
2	MME118D008	Mechanical Vibrations	3	1	0	4
3	MME18D003	Advanced Finite Element Analysis	3	1	0	4
4	MME18D010	Creep, Fatigue and Fracture	3	1	0	4
5	MME18DEXX	Elective I	3	1	0	4
6	MME18DEXX	Elective II	3	1	0	4
7	MME18DL02	Vibration Analysis Lab	0	0	4	2
Total			18	6	4	26

III SEMESTER						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MME18D012	Design of Material Handling Equipments	3	1	0	4
2	MME18DEXX	Elective III	3	0	0	3
3	MME18DEXX	Elective IV	3	0	0	3
4	MME18DL03*	Project Phase I	0	0	6	3
Total			9	1	6	13

*Students should identify the topic of the Project and should collect the literatures and datas, at the end of the semester the students should submit their Project Phase-I report to the Department and Viva-Voce examination will be conducted with external examiners and this carries 3 credits



M.Tech – DESIGN ENGINEERING (FULL TIME)

IV SEMESTER						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MME18DL04**	Project Phase II	0	0	24	12
Total			0	0	24	12

**Student should have presented a paper on the project area in National or International Conference/Journals and should attach the certificate in proof and the published paper in the project report.

TOTAL NO. OF CREDITS : 75

List of Electives (Elective – I & II)						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MME18DE01	Design and Analysis of Experiments	3	1	0	4
2	MME18DE02	Optimization in Design	3	1	0	4
3	MME18DE03	Computational fluid Dynamics	3	1	0	4
4	MME18DE04	Tribology in Design	3	1	0	4
5	MME18DE05	Advanced Machine Tool Design	3	1	0	4
6	MME18DE06	Product Design and Development Strategies	3	1	0	4
7	MME18DE07	Vibration control and conditions monitoring	3	1	0	4

List of Electives (Elective – III & IV)						
S.No	Subject Code	Title of Subject	L	T	P	C
1	MME18DE08	Robotics and Sensors	3	0	0	3
2	MME18DE09	Composite Materials and Mechanics	3	0	0	3
3	MME18DE10	Mechatronics in Manufacturing System	3	0	0	3
4	MME18DE11	Theory of plasticity	3	0	0	3
5	MME18DE12	Product Life Cycle Management	3	0	0	3
6	MME18DE13	Quality Engineering and Non Destructive Testing	3	0	0	3
7	MME18DE14	Internet of Things (IoT) in Manufacturing	3	0	0	3



M.Tech – DESIGN ENGINEERING (FULL TIME)

MMA180002 APPLIED MATHEMATICS FOR DESIGN ENGINEERS 3 1 0 4
(Common to M.Tech- DESIGN and CAD/CAM)

OBJECTIVES: At the end of this course the student will learn

- Analytical functions and different transform methods
- To solve the differential equations using finite difference methods

(Common to I yr. / I Sem. M.Tech(Full Time) – Mechanical(Design, CAD-CAM))
[2018 batch onwards]

UNIT I NUMERICAL SOLUTIONS TO ALGEBRAIC EQUATIONS 12 Hrs

Systems of linear equations: Gauss Elimination method, pivoting techniques, Thomas algorithm for tridiagonal system – Jacobi, Gauss Seidel, SOR iteration methods - Systems of nonlinear equations: Fixed point iterations, Newton Method, Eigenvalue problems: power method, inverse power method- Faddeev – Leverrier Method.

UNIT II NUMERICAL SOLUTIONS TO DIFFERENTIAL EQUATIONS 12 Hrs

Runge Kutta Methods for system of IVPs, numerical stability, Adams-Bashforth multistep method, solution of stiff ODEs, BVP: Shooting method, Direct method, Orthogonal collocation method, Orthogonal collocation with finite element method, Galerkin finite element method.

UNIT III FINITE DIFFERENCE METHODS FOR PARABOLIC EQUATIONS 12 Hrs

Parabolic equations: explicit and implicit finite difference methods, weighted average approximation - Dirichlet and Neumann conditions – Two dimensional parabolic equations – ADI method.

UNIT IV FINITE DIFFERENCE METHODS FOR HYPERBOLIC EQUATIONS 12 Hrs

First order hyperbolic equations – method of characteristics, different explicit and implicit methods; numerical stability analysis, method of lines – Wave equation: Explicit scheme- Stability of above schemes.

UNIT V FINITE DIFFERENCE METHODS FOR ELLIPTIC EQUATIONS 12 Hrs

Laplace and Poisson's equations in a rectangular region: Five point finite difference schemes, Leibmann's iterative methods, Dirichlet and Neumann conditions – Laplace equation in polar coordinates: finite difference schemes – approximation of derivatives near a curved boundary while using a square mesh.

Total no. of hrs: 60

Reference Books:

- 1) Saumyen Guha and Rajesh Srivastava, "Numerical methods for Engineering and Science", Oxford Higher Education, New Delhi, 2010.
- 2) Gupta S.K., "Numerical Methods for Engineers", New Age Publishers, 1995
- 3) Burden, R.L., and Faires, J.D., "Numerical Analysis – Theory and Applications", Cengage Learning, India Edition, New Delhi, 2009.
- 4) Jain M. K., Iyengar S. R., Kanchi M. B., Jain , "Computational Methods for Partial Differential Equations", New Age Publishers, 1993.
- 5) Morton K.W. and Mayers D.F., "Numerical solution of partial differential equations", Cambridge University press, Cambridge, 2002.
- 6) Sastry S.S., *Introductory Methods of Numerical Analysis*, Prentice Hall of India, (2003).



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18D001 **CONCEPTS OF ENGINEERING DESIGN** **3 0 0 3**

OBJECTIVE: At the end of this course the student will learn

- Process and methods of designing and quality management and quality tools

UNIT I: DESIGNPROCESS:

9Hrs

The Design Process - Morphology of Design - Design Drawings - Computer Aided Engineering - Designing of Standards - Concurrent Engineering - Product Life Cycle - Technological Forecasting - Market Identification - Competition Benchmarking - Systems Engineering - Life Cycle Engineering - Human Factors in Design -Industrial Design.

UNIT II: DESIGN METHODS

9Hrs

Creativity and Problem Solving - Product Design Specifications - Conceptual Design - Decision Theory - Decision Tree - Embodiment Design - Detail Design - Mathematical Modeling - Simulation - Geometric Modeling - Finite Element Modeling - Optimization - Search Methods - Geometric Programming - Structural and Shape Optimization.

UNIT III: MATERIAL SELECTION – DESIGN AND PROCESSING

9Hrs

Material Selection Process - Economics - Cost Vs Performance - Weighted Property Index - Value Analysis - Role of Processing in Design - Classification of Manufacturing Process - Design for Manufacture - Design for Assembly - Design for Castings, Forging, Metal Forming, Machining and Welding - Residual Stresses - Fatigue, Fracture and Failure.

UNIT IV: ENGINEERING STATISTICS AND RELIABILITY

9Hrs

Probability - Distributions - Test of Hypothesis - Design of Experiments - Reliability Theory - Design for Reliability – Reliability Centered Maintenance.

UNIT V: QUALITY ENGINEERING

9Hrs

Total Quality Concept - Quality Assurance - Statistical Process Control - Taguchi Methods - Robust Design – Failure Mode and Effect Analysis.

Total No. of Hrs : 45

REFERENCES

1. Pahl, G. and Beitz, W. (1984) *Engineering Design. Springer - Verlag*
2. Karl Ulrich, T. and Eppinger Steven, D. (2000) *Product Design and Development. McGraw Hill Edition*
3. Dieter George, E. (1991) *Engineering Design - A Materials and Processing Approach. McGraw Hill,*
4. *International Editions, Mechanical Engineering Series*
5. Suh, N.P. (1990) *The principles of Design. Oxford University Press*
6. Ray, M.S. (1985) *Elements of Engg. Design. Prentice Hall Inc*



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18D002 COMPUTER AIDED DESIGN AND MANUFACTURING 3 1 0 4

OBJECTIVES: At the end of this course the student will learn

- Various mathematical approaches to design
- Manufacturing, planning and control

UNIT I: INTRODUCTION

12Hrs

Definition, Interactive Computer Graphics-Line and Circle plotting algorithm (DDA & Bresenham's), Transformation, Translation, Rotation, Scaling & Mirroring, Concatenated Transformation, Clipping Algorithm, Hidden Line Removal, Explicit and implicit equations, parametric equations.

UNIT II: SPLINES AND CURVES

12Hrs

Cubic Splines-Algebraic and geometric form of cubic spline, tangent vectors, parametric space of a curve, blending functions, four point form, reparametrization, truncating and subdividing of curves. Graphic construction and interpretation, composite pc curves. Bezier Curves-Bernstein basis, equations of Bezier curves, properties, derivatives. B-Spline basis, equations, knot vectors, properties, and derivatives.

UNIT III: SURFACES AND SOLIDS

12Hrs

Bi-cubic surfaces, Coon's surfaces, Bezier surfaces, B-Spline surfaces, surfaces of revolutions, Sweep surfaces, ruled surfaces, tabulated cylinder, bilinear surfaces, Gaussian curvature. Tri-cubic solid, Algebraic and geometric form. 3D wire frames, Boundary representation, Half space modeling, spatial cell, cell decomposition, classification problem.

UNIT IV: PRODUCTION PLANNING AND CONTROL

12Hrs

Group Technology, Computer Aided Process Planning: Retrieval & Generative CAPP, Production Planning, Material Requirement Planning (MRP), mechanism of MRP, benefits, and Capacity Planning. Production Control, Factory Data Collection system, Just-in-Time, Automated Material Handling System, Data Flow in Manufacturing System, Product Data Management System.

UNIT V: COMPUTER NUMERICAL CONTROL

12Hrs

Introduction to NC, Principles and Classifications of CNC, DNC, Part Programming, Adaptive control machining systems, adaptive control optimization system, adaptive control constraint system, applications to machining processes, computer process monitoring, hierarchical structure of computers in manufacturing, and computer process control.

Total No. of Hrs: 60

REFERENCES

1. Ibrahim Zeid, *CAD/CAM*. Tata McGraw Hill
2. Roger and Adams, *Elements of Computer Graphics*. Tata McGraw Hill
3. Micheal Mortenson, *E. Geometric Modeling*. McGraw Hill Publishers
4. Lalit Narayan, K. Mallikarjuna Rao, K. and Sarcar, M.M.M. *Computer Aided Design and Manufacturing*, PHI Publishers



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18D009 ADVANCED STRENGTH OF MATERIALS 3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Behaviour of the material under different types of loads

UNIT I: INTRODUCTION

12Hrs

Load-Stress and Load-Deflection, Stress-strain relations, Failure and limits on design
Theories of Stress and Strain- Definition of stress at a point, Stress notation, Symmetry of the stress array and stress on an arbitrarily oriented plane, Transformation of stress, Principal stresses, Differential equations of a deformable body, Deformation of a Deformable body, Strain Theory, Transformation of strain, Principal strains, Small displacement theory, Strain measurement

UNIT II: TORSION

12Hrs

Torsion of Prismatic bar of circular cross section, Saint-Venant's semi inverse method, Linear elastic solution, Narrow rectangular cross section, Hollow thin-wall torsion members, Multiply connected cross section, Thin wall torsion members with restrained ends, Numerical solution of torsion problems

UNIT III: BENDING

12Hrs

Definition of shear centre in bending, Symmetrical and non-Symmetrical bending, Bending stresses in beams subjected to non-Symmetrical bending, Deflections of straight beams subjected to non-Symmetrical bending, Effect of Inclined loads

UNIT IV: CURVED BEAMS

12Hrs

Introduction, Circumferential stresses in a curved beam, Radial stresses in curved beams, Correction of circumferential stresses in curved beams, Deflection of curved beams, Statically indeterminate curved beams, Closing ring subjected to a concentrated load

UNIT V: CONTACT STRESSES

12Hrs

Introduction, the problem of determining contact stresses, Geometry of the contact surface, Notation and meaning of terms, Expressions for Principal stresses, Method of computing contact stresses, Deflection of bodies in point contact, Stress for two bodies in line contact, Loads normal to contact area and Tangent to contact area, Problems

Total No. of Hrs : 60

REFERENCES

1. Arthur Boresh, P. *Advanced Mechanics of Materials*. John Wiley & sons, Inc
2. Egor Popov, P. (1997) *Engineering Mechanics of Solids*. Prentice Hall of India
3. Srinath, L.N. *Advanced Mechanics of Solids*. Tata McGraw Hill Publishing Company Ltd
4. Junarkar, S.B. (1995) *Mechanics of Structures*. Vol.1, 21st Edition, Charotar Publishing House.



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18D005

ADVANCED MATERIALS TECHNOLOGY

3 0 0 3

OBJECTIVE: At the end of this course the student will learn

- Properties and characteristics of different types of materials

UNIT I: INTRODUCTION TO FERROUS MATERIALS.

9Hrs

Plain carbon steels, their properties and application: plain carbon steels, effects of alloying elements in plain carbon steels. Alloy steels, tools steels, stainless steels, low and high temperature resisting steels, high strength steels, selections, specifications, form and availability of steel. Cast irons-white, grey, modular malleable and alloy cast irons. Recognised patterns of distribution of graphite flakes in grey cast iron

UNIT II: NONFERROUS MATERIALS

9Hrs

Ultra light materials. Properties and application, brasses, bronzes, cupro-nickel alloys, aluminium, magnesium and titanium alloys, bearing materials. Heat treatment of nonferrous materials– solutionizing, Aging and precipitations hardening.

UNIT III: NANOMATERIAL

9Hrs

Introduction to Nanomaterials-types-Nano powder-Nanodots-Nanotubes- Nano fluids-Fullerene-Different shape-properties and characteristics and applications. Refractory materials and coatings for high temperature applications. Smart Materials-introduction, types and applications. Thin film shape memory alloys

UNIT IV: BIO-MATERIALS AND COMPOSITES

9Hrs

Classes and application of materials in medicine and dentistry. Stress strain behaviour of bone. The mechanical properties including elasticity, hardness, viscoelasticity, surface and fatigue properties of skin; soft tissues; bone; Biocompatible materials and its applications. The effects of degradation and corrosion. Composites- metal, polymers and ceramics- applications

UNIT V: NUCLEAR MATERIALS

9Hrs

Introduction to nuclear materials. Materials for nuclear fuel in fission and fusion reactors, Fissile and fertile materials. Control & Construction Materials for Nuclear reactors, Moderators, Heat Exchangers. Radiation proof materials. Brief discussion of safety and radioactive waste disposal.

Total No. of Hrs: 45

REFERENCES

1. Buddy Ratner, D. Hoffman, A.S. and Lemons, J.E. (2004) *Biomaterials Science- An Introduction to Materials in*
1. *Medicine*. Second Edition, Academic Press
2. Joon Park, B. & Lakes Roderic, S. (1992) *Biomaterials: An Introduction*. Second Edition, Plenum Press
3. Edited by Davis, J. R. (2003) *Handbook of Materials for Medical Devices*. ASM international
4. Lamarsh, J.R. *Introduction to Nuclear Engineering*
5. Callister, W.D. Jr, *Material Science & Engineering Addition*. Wesley Publishing Co
6. Van Vlack, *Elements of Material Science & Engineering*. John Wiley & Sons



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DL01

DESIGN ANALYSIS LAB

0 0 4 2

OBJECTIVE: At the end of this course the student will learn

- Design, modeling and analysis using computer softwares and tools

I MODELLING:

- Introduction to modelling techniques- Type of modelling- wire frame, surface and solid modelling — constructive solid modelling and B-rep modelling- Feature based and parametric modelling etc.
- Generation of surfaces of revolution, surfaces of extrusion, surfaces by skinning operation etc.
- Creation of different views-importing models from other soft wares-Data base management.

(Exercises will be given using packages like PROE/CATIA/ Unigraphics etc.)

II. ANALYSIS:

- Introduction to FEM-Analysis softwares -ANSYS / NASTRAN/NISA/COSMOS/I-DEAS etc.
- Structural and fluid analysis.- One dimensional, Two dimensional and Three dimensional Elements Based Problems.
- Thermal Analysis - Conduction, Convection and Radiation heat transfer Problems.

III. MATLAB

- Introduction to MATLAB
- Study of different MATLAB tools
- Arithmetic and logical operators
- Matrix operation using MATLAB
- Mathematical equations solution
- Generation of trigonometrically wave functions
- Introduction to SIMULINK
- Flow control statements and graphs

Total No. of Hrs : 60



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DL02

VIBRATION ANALYSIS LAB

0 0 4 2

OBJECTIVE: At the end of this course the student will learn

- To measure and analyse various types of mechanical vibrations

VIBRATION TYPES AND MEASUREMENTS:

Study of types of vibration-Longitudinal, transverse and torsional vibration - degree of freedom.

- Damped free vibration of a single degree of freedom spring mass system.
- Transverse Free vibration of a cantilever beam.
- Transverse free vibration of a simply supported beam.
- Determination of critical speed of a shaft.
- Torsional vibration of a single rotor system.
- Balancing of rotating masses using Dynamic balancing Machine.
- Lab view for vibration and noise.

VIBRATION ANALYSIS USING FFT ANALYSER IN THE FOLLOWING AREAS:

- Power train.
- Motor, Pumps.
- Machine tools like Lathe, Milling, drilling etc.,

Total No. of Hrs: 60



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18D012 DESIGN OF MATERIAL HANDLING EQUIPMENTS 3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Design of different types of material handling systems used for engineering and process industries

UNIT I: INTRODUCTION TO MATERIALS HANDLING EQUIPMENT 12Hrs

Overview - consideration in material handling system design, ten principles of material handling. Types of material handling equipments-trolleys, industrial trucks, AGV, monorails and other rail guided vehicles, conveyors, cranes, hoists and elevators.

UNIT II: DESIGN OF HOISTS 12Hrs

Design of hoisting elements: Welded and roller chains - Hemp and wire ropes - Design of ropes, pulleys, pulley systems, sprockets and drums, Load handling attachments. Design of forged hooks and eye hooks – crane grabs - lifting magnets - Grabbing attachments - Design of arresting gear - Brakes: shoe, band and cone types.

UNIT III: DRIVES OF HOISTING GEAR 12Hrs

Hand and power drives - Travelling gear - Rail travelling mechanism - cantilever and monorail cranes - slewing, jib and luffing gear - cogwheel drive - selecting the motor ratings.

UNIT IV: CONVEYORS 12Hrs

Types - description - design and applications of Belt conveyors, apron conveyors and escalators
Pneumatic conveyors, Screw conveyors and vibratory conveyors.

UNIT V: ELEVATORS 12Hrs

Bucket elevators: design - loading and bucket arrangements - Cage elevators - shaft way, guides, counter weights, hoisting machine, safety devices - Design of fork lift trucks.

Total No. of Hrs: 60

NOTE: Use of Approved Data Book is permitted in examination

REFERENCES

1. Rudenko, N. (1970) *Materials handling equipment*. ELNvee Publishers
2. Mikell Groover, P. (2006) *Automation, Production system and computer integrated Manufacturing*. Second Edition, Prentice Hall of India Pvt. Ltd
3. Alexandrov, M. (1981) *Materials Handling Equipments*. MIR Publishers
4. Boltzharol, A. (1958) *Materials Handling Handbook*. The Ronald Press Company
5. P.S.G. Tech, (2003) *Design Data Book*. Kalaikathir Achchagam
6. Lingaiah. K. and Narayana Iyengar, (1983) *Machine Design Data Hand Book*. Vol.1 & 2, Suma Publishers
7. Spivakovsy, A.O. and Dyachkov, V.K. (1985) *Conveying Machines*. Volumes I and II, MIR Publishers



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M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DL03

PROJECT PHASE I

0 0 6 3

- Students should select the area of the project work and complete the literature survey.
- Student should identify the problem of study and start the work.
- Students are expected to do the project work individually.
- A guide will be allotted to each student based on the area of the Project work.
- Project reviews will be conducted once in a fortnight to assess the development of the project work.
- At the end of the semester students should submit a report of the work completed and should appear for a Project Viva-voce examination conducted by the internal examiner.
- Continuous assessment mark (50 marks) will be awarded based on the performance in the reviews.
- End semester mark (50 marks) will be awarded for project viva voce examination.



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DL04

PROJECT PHASE II

0 0 24 12

- Students are expected to do a Project work either in an Industry or at the University in the area of specialization individually.
- Each student will be allotted a guide based on the area of Project work

Number of reviews will be conducted during the semester to monitor the development of project. Students have to submit the thesis at the end of the semester and appear for the Project Viva-Voce examination conducted by one internal examiner and one external examiner.

It is mandatory that the student should have presented his project work as a technical paper in National/international conference /Journals. A copy of the certificate in proof of paper presentation should be enclosed in the project report.

50% weightage (100 marks) will be given for the continuous assessment and 50% weightage (100 marks) for the Project viva a voce examination.



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE01 DESIGN AND ANALYSIS OF EXPERIMENTS 3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- To analyse the experiments using statistical tools

UNIT I: EXPERIMENTAL DESIGN FUNDAMENTALS 9Hrs

Importance of experiments, experimental strategies, basic principles of design, terminology, ANOVA, steps in experimentation, sample size, normal probability plot, linear regression model.

UNIT II: SINGLE FACTOR EXPERIMENTS 12Hrs

Completely randomized design, Randomized block design, Latin square design. Statistical analysis, estimation of model parameters, model adequacy checking, pair wise comparison tests.

UNIT III: MULTIFACTOR EXPERIMENTS 13Hrs

Two and three factor full factorial experiments, 2^k factorial Experiments, Confounding and Blocking designs.

UNIT IV: SPECIAL EXPERIMENTAL DESIGNS 13Hrs

Fractional factorial design, nested designs, Split plot design, Introduction to Response Surface Methodology, Experiments with random factors, rules for expected mean squares, approximate F- tests.

UNIT V: TAGUCHI METHODS 13Hrs

Steps in experimentation, design using Orthogonal Arrays, data analysis, Robust design- control and noise factors, S/N ratios, parameter design, case studies.

Total No. of Hrs : 60

REFERENCES

1. Montgomery, D.C. (2003) *Design and Analysis of experiments*. John Wiley and Sons
2. Nicolo Belavendram, (1995) *Quality by Design; Taguchi techniques for industrial experimentation*. Prentice Hall
3. Phillip Rose, J. (1996) *Taguchi techniques for quality engineering*. McGraw Hill



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE02

OPTIMIZATION IN DESIGN

3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Optimization techniques and its application in design and manufacturing

UNIT I: CLASSICAL OPTIMIZATION TECHNIQUES

12Hrs

Single variable optimization with and without constraints, Multi-variable optimization without constraints, multi-variable optimization with constraints– method of Lagrange multipliers, Kuhn-Tucker conditions.

UNIT II: NUMERICAL METHODS FOR OPTIMIZATION

12Hrs

Nelder Mead's Simplex search method, Gradient of a function, steepest descent method, Newton's method, types of penalty methods for handling constraints.

UNIT III: GENETIC ALGORITHM (GA)

12Hrs

Differences and similarities between conventional and evolutionary algorithms, working principle, reproduction, crossover, mutation, termination criteria, different reproduction and crossover operators, GA for constrained optimization, draw backs of GA, multi-objective GA, Non-dominated sorted GA, convergence criterion, applications of multi-objective problems.

UNIT IV: APPLICATIONS OF OPTIMIZATION IN DESIGN AND MANUFACTURING SYSTEMS

12Hrs

Some typical applications like optimization of path synthesis of a four-bar mechanism, minimization of weight of a cantilever beam, optimization of springs and gears, general optimization model of a machining process, optimization of arc welding parameters, and general procedure in optimizing machining operations sequence.

UNIT V: INTRODUCTION TO NEURAL NETWORKS

12Hrs

Introduction, Humans and Computers, Organization of the Brain, Biological Neuron, Biological and Artificial Neuron Models, Hodgkin-Huxley Neuron Model, Integrate and- Fire Neuron Model, Spiking Neuron Model, Characteristics of ANN, McCulloch- Pitts Model, Historical Developments, Potential Applications of ANN.

Total No. of Hrs: 60

REFERENCES

1. Jasbir Arora, *Optimal design*. McGraw Hill (International) Publishers
2. Kalyanmoy Deb, *Optimization for Engineering Design*. PHI Publishers
3. Rao, S.S. *Engineering Optimization*. New Age Publishers
4. Johnson Ray, C. (1990) *Optimum Design of mechanical elements*. John Wiley & Sons
5. Kalyanmoy Deb, *Multi objective Genetic algorithms*. PHI Publishers
6. Hertz, Krogh and Palmer, *Introduction to the theory of Neural Computation*
7. Yegnanarayana, B. *Artificial Neural Networks*. PHI Publishers
8. David Goldberg, E. (1989) *Genetic Algorithms*. Addison Wesley



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE03 COMPUTATIONAL FLUID DYNAMICS 3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Formulation and analysis of problems on fluid dynamics

UNIT I: GOVERNING DIFFERENTIAL EQUATIONS AND FDM 12Hrs

Classification, Initial and Boundary Conditions, Initial and Boundary value problems. Finite Difference Method, Central, Forward, Backward Difference, Uniform and Non-uniform Grids, Numerical Errors, Grid Independence Test.

UNIT II: CONDUCTION HEAT TRANSFER 12Hrs

Steady one-dimensional conduction, Two and Three dimensional Steady state problems, Transient One dimensional and Two dimensional problems.

UNIT III: INCOMPRESSIBLE FLUID FLOW 12Hrs

Governing Equations, Stream function – Vorticity Method, Determination of Pressure for Viscous flow, Simple procedure of Patankar and Spalding, Computation of Boundary layer flow, Finite Difference Approach.

UNIT IV: CONVECTION HEAT TRANSFER AND FEM 12Hrs

Steady One Dimensional and Two Dimensional Convection-Diffusion, Unsteady One Dimensional Convection- Diffusion, Unsteady Two Dimensional Convection – Diffusion – Introduction to Finite Element Method-Solution of Steady Heat Conduction by FEM- Incompressible flow – Simulation by FEM.

UNIT V: TURBULENCE MODELS 12Hrs

Algebraic models –One Equation model, K-I Models, Standard, High and Low Reynolds Number models, Prediction of Fluid flow and Heat transfer using Standard Codes.

Total No. of Hrs: 60

REFERENCES

1. Muralidhar, K. and Sundararajan, T. (1995) *Computational Fluid Flow and Heat Transfer*. Narosa Publishing House
2. Ghoshdasdidar, P.S. (1998) *Computer Simulation of Flow and Heat Transfer*. Tata McGraw Hill Publishing Company Limited
3. Subhas, V. Patankar, (1980) *Numerical Heat Transfer Fluid Flow*. Hemisphere Publishing Corporation
4. Taylor, C. and Hughes, J.B. (1981) *Finite Element Programming of Navier Stoke Equation*. Pine Ridge Press Ltd
5. Anderson, D.A. Tannehill, J.C. and Pletcher, R.H. (1984) *Computational Fluid Mechanics and Heat transfer*. Hemisphere Publishing Corporation
6. Fletcher, C.A.J. (1987) *Computational Techniques for Fluid Dynamics-Fundamental and General Techniques*. Springer –Verlag
7. Fletcher, C.A.J. (1987) *Computational Techniques for Different Flow Categories*. Springer – Verlag
8. Bose T.K. (1997) *Numerical Fluid Dynamics*. Narosa Publishing House



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE04

TRIBOLOGY IN DESIGN

3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Influence of behaviour of friction, wear and lubrication on design

UNIT I: SURFACES, FRICTION AND WEAR

12Hrs

Topography of the surfaces - Surface features - Surface interaction - Theory of Friction - Sliding and Rolling Friction, Friction properties of metallic and non-metallic materials - friction in extreme conditions - Wear, types of wear - Mechanism of wear - Wear resistance materials - Surface treatment - Surface modifications -Surface coatings.

UNIT II: LUBRICATION THEORY

12Hrs

Lubricants and their physical properties, lubricants standards - Lubrication regimes- Hydrodynamic lubrication - Reynolds Equation, thermal, inertia and turbulent effects - Elasto hydrodynamic and plasto hydrodynamic and magneto hydrodynamic lubrication - Hydro static lubrication .

UNIT III: DESIGN OF FLUID FILM BEARINGS

12Hrs

Design and performance analysis of thrust and journal bearings - Full, partial, fixed and pivoted journal bearings design - Lubricant flow and delivery - power loss, Heat and temperature, rotating loads and dynamic loads in journal bearings - Hydrostatic Bearing design.

UNIT IV: ROLLING ELEMENT BEARINGS

12Hrs

Geometry and Kinematics - Materials and manufacturing processes - contact stresses - Hertzian stress equation - Load divisions - Stresses and deflection - Axial loads and rotational effects, Bearing life capacity and variable loads - ISO standards - Oil films and their effects - Rolling Bearings Failures.

UNIT V: TRIBO MEASUREMENT IN INSTRUMENTATION

12Hrs

Surface topography measurements - Electron microscope and friction and wear measurements - Laser method - Instrumentation - International standards -Bearings performance measurements - Bearing vibration measurement.

Total No. of Hrs: 60

REFERENCES

1. Cameron, A. (1981) *Basic Lubrication Theory*. Ellis Herward Ltd.
2. Hulling, J. (Editor), (1984) *Principles of Tribology*. MacMillan.
3. Williams, J.A. (1994) *Engineering Tribology*. Oxford Univ. Press.
4. Neale, M.J. (1995) *Tribology Hand Book*. Butterworth Heinemann.
5. <http://www.csetr.org/link.htm>
6. <http://www.me.psu.edu/research/tribology.htm>



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE06

**PRODUCT DESIGN AND DEVELOPMENT
STRATEGIES**

3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- Product design considerations and strategies of innovative product development

UNIT I: INTRODUCTION

11Hrs

Essential factors of product design- requirements of good design- factors affecting product design- product development process tools- Design by evolution and innovation- Asimow's model- Journeys in product development- product engineering – nature and scope- Product design practice in industry.

UNIT II: CREATIVITY

12Hrs

Creative thinking and organizing for product innovation criteria – method and tools for directed creativity – challenges of quality management – Case studies – Mumbai's Dabbawalas – creativity by less learned- Creativity on wheel chair – MARICO (case study)- Patent –design patents- patent application steps – sale of patent rights.

UNIT III: DESIGN CONSIDERATIONS

14Hrs

Functional and production design – form design – influence of basic design, mechanical loading and material on form design – Design for manufacture and assembly – Design for robustness – Design for production – Design for stiffness and rigidity – strength consideration in product design – optimization in design – Project analysis – Mechanical estimating and costing.

UNIT IV: PRODUCT DEVELOPMENT STRATEGIES

11Hrs

Planning and preparation – Resources – Talent –striving, thinking, relating – Quality assurance in product design – Strategy for product development – Case studies.

UNIT V: HUMAN AND VALUE ENGINEERING

12Hrs

Human beings as applicator of forces – Anthropometry – design of controls and displays – man/machine information exchange – aesthetic and ergonomic considerations – Value engineering – maximum value- Normal degree of value – value analysis of job plan – Idea generation check-list – Cost reduction through value engineering case study on tap switch control assembly – Economic factors influencing design – Material and process selection.

Total No. of Hrs: 60

REFERENCES

1. *Kavin & Krishn, Product Design Techniques in reverse engineering & New product development, Pearson*
1. *Education*
2. *Paul Plsek, E. Creativity, Innovation and Quality. Prentice - Hall of India Private Limited*
3. *Jones, J.C. (1970) Design Methods. Interscience*
4. *Buhl, H. (1960) Creative Engineering Design. Iowa State University Press*
5. *Dieter, G.E. (1983) Engineering Design. McGraw Hill*
6. *Niebel, B.W. & Draper, A.B. (1974) Product Design and Process Engineering. McGraw Hill*
7. *Harry Peck, (1973) Designing for Manufacturing. Sir Issac Pitman and Sons Ltd.*



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE07 VIBRATION CONTROL AND CONDITIONS MONITORING 3 1 0 4

OBJECTIVE: At the end of this course the student will learn

- To provide the detail knowledge about nonlinear and random vibration with fault diagnosis of machinery

UNIT I: INTRODUCTION

9Hrs

Review of fundamentals of single degree of freedom systems- Two degree of freedom systems- Multi degree freedom systems- Continuous system- Determination of Natural frequencies and mode shapes. Numerical methods in vibration analysis.

UNIT II: VIBRATION CONTROL

12Hrs

Introduction – Reduction of vibration at source- Control of vibration- By structural Design- Material selection- Located Additions- Artificial Damping- Resilient Isolation, Vibration Isolation- Vibration Absorbers.

UNIT III: ACTIVE VIBRATION CONTROL

12Hrs

Introduction - Concepts and Applications- Review of Smart Materials- Types and Characteristics Review of Smart Structures- Characteristic Active Vibration in Smart Structures.

UNIT IV: CONDITION BASED MAINTANENCE PRINCIPLES AND APPLICATION

15Hrs

Introduction- Condition Monitoring methods- The design of Information system, Selecting Methods of Monitoring, Machine Condition Monitoring and Diagnosis- Vibration Severity Criteria Machine Maintenance Techniques- Machine Condition Monitoring Techniques- Vibration Monitoring Techniques- Instrumentation Systems- Choice of Monitoring Parameter.

UNIT V: DYNAMIC BALANCING AND ALIGNMENT OF MACHINERY

12Hrs

Introduction, Dynamic Balancing of Robots, Field Balancing in one Plane, Two Planes and in Several Planes Machinery Alignment, “Rough” Alignment methods- The face Periphery Dial Indicator Method- Reverse indicator method

Total No. of Hrs: 60

REFERENCES

1. Singiresu S.Rao. “Mechanical Vibration”. Addison- Wesley Publishing Co.2004
2. Rao J.S. “Vibratory Condition Monitoring of Machines” CRC Press. 2000.
- 3.J.O. Den Hartog- “Mechanical Vibrations” McGraw Hill New York.1985.
- 4.Science Elsevier- “Hand book of Condition Monitoring” ELSEVIER SCIENCE,1996.
- 5.<https://www.overdrive.com/media/118481/vibration-with-control>



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE08

ROBOTICS AND SENSORS

3 0 0 3

OBJECTIVE: At the end of this course the student will learn

- Concepts, design, application and control of robotics

UNIT I: INTRODUCTION

9Hrs

Basic concepts-Robot anatomy-robot configurations-Basic Robot motions-Types of drives-Applications-Material Handling-Processing-Assembly and Inspection -Safety considerations.

UNIT II: TRANSFORMATIONS AND KINEMATICS

9Hrs

Vector operations-Translational transformations and Rotational transformations-Properties of transformation
Matrices-Homogeneous transformations and Manipulator-Forward solution-Inverse solution

UNIT III: CONTROLS AND END EFFECTORS

9Hrs

Control system concepts-Analysis-control of joints-Adaptive and optimal control-End effectors-Classification-Mechanical-Magnetic-Vacuum-Adhesive-Drive systems-Force analysis and Gripper design

UNIT IV: ROBOT PROGRAMMING

6Hrs

Methods -Languages-Computer control and Robot Software-VAL system and Language

UNIT V: SENSORY DEVICES

12Hrs

Non-optical and optical position sensors-Velocity and Acceleration-Range-Proximity-touch-Slip-Force-Torque-Machine vision-Image components-Representation - Hardware-Picture coding-Object recognition and Categorization-Software consideration- Case Studies

Total No. of Hrs: 45

REFERENCES

1. Fu, K.S. Gonzalez, R. and Lee, C.S.G. (1987) *Robotics control, sensing, vision, and Intelligence.* McGraw Hill Book Co
2. Klafter, R.D. Cmielewski, T.A. and Negin, M. (1994) *Robot Engineering an Integrated approach.* New Prentice Hall of India
3. Deb, S.R. (1994) *Robotics Technology and Flexible Automation.* Tata McGraw Hill Publishing Co, Ltd
4. Craig J.J. (1999) *Introduction to Robotics Mechanics and Control.* Addison Wesley
5. Groover, M.P. (1995) *Industrial robotics Technology, programming and applications.* McGraw Hill Book Co
6. <http://www.robotics.com>



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE10 MECHATRONICS IN MANUFACTURING SYSTEMS 3 0 0 3

OBJECTIVE: At the end of this course the student will learn

- Usage of combination of mechanical and electronic systems in manufacturing

UNIT I: INTRODUCTION

8Hrs

Introduction to Mechatronics - Systems - Mechatronics in Products - Measurement Systems - Control Systems - Traditional design and Mechatronics Design

UNIT II: SENSORS AND TRANSDUCERS

9Hrs

Introduction-Performance terminology-Displacement, position and proximity - Velocity and Motion-Fluid pressure-Temperature sensors - Light sensors - Selection of sensors-Signal processing-Servo systems

UNIT III: MICROPROCESSORS IN MECHATRONICS

12Hrs

Introduction-Architecture-Pin configuration-Instruction set-Programming of Microprocessors using 8085 instructions-Interfacing input and output devices-Interfacing D/A Converters and A/D Converters-Applications-Temperature control-Stepper motor control-Traffic light controller

UNIT IV: PROGRAMMABLE LOGIC CONTROLLERS

8Hrs

Introduction-Basic structure-input/output processing-programming-Mnemonics Timers, Internal relays and counters-Data handling-Analog input/output-Selection of PLC.

UNIT V: DESIGN OF MECHATRONICS SYSTEM

8Hrs

Designing-Possible design solutions-Case studies of Mechatronics systems

Total No. of Hrs: 45

REFERENCES

1. Michael, B.H. and David, G.A. (1999) *Introduction to Mechatronics and Measurement Systems*. McGraw Hill International Editions
2. Bradley, D.A. and Dawson, D. (1993) *Mechatronics*. Chapman and Hall
3. Gaonkar, R.S. (1998) *Microprocessors Architecture, Programming and Applications*. Wiley Eastern
4. Lawrence J.K. (2000) *Understanding Electro-Mechanical Engineering, an Introduction to Mechatronics*. Prentice Hall
5. Ghosh, P.K. and Sridhar, P.R. (1995) *0000 to 8085 Introduction to Microprocessors for Engineers and Scientists*. Second Edition, Prentice Hall
6. [Http://www.cs.indiana.edu](http://www.cs.indiana.edu).



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE11

THEORY OF PLASTICITY

3 0 0 3

OBJECTIVE: At the end of this course the student will learn

- To understand the concepts and theories of elastic and plastic deformation

UNIT I: INTRODUCTION

9Hrs

Modeling Uniaxial behaviour in plasticity. Index notation, Cartesian tensors. Yield and failure criteria Stress, stress deviator tensors. Invariants, principal, mean stresses. Elastic strain energy. Mohr's representation of stress in 2 & 3 dimensions. Haigh-Westergaard stress space. Equilibrium equations of a body. Yield criteria: Tresca's, von Mises rules, Drucker-Prager criterion, anisotropic yield criteria.

UNIT II: STRAIN AT POINT

9Hrs

Cauchy's formulae for strains, principal strains, principal shear strains, derivative strain tensor. Strain-displacement relationships. Linear elastic stress strain relations, Generalized Hooke's law, nonlinear elastic stress strain relations

UNIT III: STRESS STRAIN RELATIONSHIPS

9Hrs

Prandtl-Reuss material model. J2 deformation theory, Drucker-Prager material, General Isotropic materials. Drucker's stability postulate, normality, convexity and uniqueness for an elastic solid. Incremental stress strain relations.

UNIT IV: CRITERIA FOR LOADING AND UNLOADING

9Hrs

Elastic and plastic strain increment tensors, Plastic potential and flow rule associated with different Yield criteria, Convexity, normality and uniqueness considerations for elastic-plastic materials. Expansion of a thick walled cylinder.

UNIT V: THEORY OF PLASTICITY AND BOUNDING SURFACES

9Hrs

Loading surface, Hardening rules. Flow rule and Drucker's stability postulate. Concept of effective stress and effective strain, mixed hardening material. Problems.

Uniaxial and multiaxial loading anisotropic material behaviour, Theorems of limit analysis, Statically admissible stress field and kinematically admissible velocity field, Upper and lower bound theorems, examples and problems.

Total No. of Hrs: 45

REFERENCES

1. Chens, W.F. and Han, D.J. (1987) *Plasticity for structural engineering*. Springer – Verlag.
2. Victor E.S. *Mechanics of Materials –II*.



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE13 QUALITY ENGINEERING AND NON DESTRUCTIVE TESTING 3 0 0 3

OBJECTIVES: At the end of this course the student will learn

- TQM and its implementations
- Non destructive testing methods

UNIT I: STATISTICAL QUALITY CONTROL 9Hrs

Data presentation - Statistical measures and tools - Process capability - Confidence and tolerance limits - Control charts for variables and for fraction defectives - Theory of probability - Sampling - ABC standard - Reliability and life testing.

UNIT II: TQM SYSTEMS AND IMPLEMENTATION 9Hrs

Quality policy deployment, quality function deployment, standardization, designing for quality, manufacturing for quality. TQM IMPLEMENTATION - Steps, KAIZEN, 5S, JIT, POKAYOKE, Taguchi methods, case studies. Total Productive Maintenance (TPM) : Philosophy and Implementation Benchmarking- Type - Applications.

UNIT III: NON DESTRUCTIVE TESTING: - LIQUID PENETRANT AND MAGNETIC PARTICLE TESTS 9Hrs

Characteristics of liquid penetrants -different washable systems-Developers-applications -Methods of production of magnetic fields - Principles of operation of magnetic particle test -Applications – Advantages and Limitations.

UNIT IV: NON DESTRUCTIVE TESTING-RADIOGRAPHY 9Hrs

Sources of ray-x-ray production - properties of d and x rays- film characteristics - exposure charts - contrasts - operational characteristics of x ray equipment - applications.

UNIT V: NON DESTRUCTIVE TESTING-ULTRASONIC AND ACOUSTIC EMISSION TECHNIQUES 9Hrs

Production of ultrasonic waves - different types of waves - general characteristics of waves-pulse echo method -A,B,C scans - Principles of acoustic emission techniques - Advantages and limitations - Instrumentation - Applications.

Total No. of Hrs: 45

REFERENCES

1. Rose, J.E. (1993) *Total Quality Management. Kogan Page Ltd*
2. Barry Hull and Vernon John, (1988) *Non Destructive Testing. MacMillan*
3. (1976) *American Society for Metals, Metals Hand Book. Vol. II*
4. (1990) *Progress in Acoustic Emission. Proceedings of 10th International Acoustic Emission Symposium, Japanese society for NDI*
5. [Http://www.sisndt.com](http://www.sisndt.com)
6. [Http://www.iuk'tu-harburg.de](http://www.iuk'tu-harburg.de)



M.Tech – DESIGN ENGINEERING (FULL TIME)

MME18DE14 INTERNET OF THINGS (IoT) IN MANUFACTURING 3 0 0 3

OBJECTIVES: At the end of this course the student will learn

- Basics and applications of Internet of Things in Manufacturing
- Supply chain Management and Predictive maintenance
- Inventory optimization and queuing networks.

UNIT -I Introduction To Industrial Internet Of Things (IIOT) 9 Hrs

Introduction, Physical design of IoT, Logical design of IoT, IoT enabling technologies, Domain specific IoTs, IoT design methodology, IoT physical devices (such as Raspberry Pi, pcDuino, Beaglebone black, Cubieboard) , Introduction to cloud computing: cloud models, cloud service examples

UNIT - II Supply Chain Management 9 Hrs

Building blocks of a supply chain network. Business processes in supply chains. Types of supply chains and examples. Strategic, tactical, and operational decisions in supply chains. Supply chain performance measures. Best practice supply chain solutions. Internet-enabled supply chains: e-marketplaces, e-procurement, e-logistics, e-fulfillment, customer relationship management, web services, Rosettanet, ERP and supply chains, supply chain automation, and supply chain integration

UNIT - III Operating Efficiency 9 Hrs

Production flow monitoring - optimize flow, eliminate waste and avoid unnecessary work in process inventory. **Remote equipment management** - including setting specific limits and parameters to save energy and costs. Smart manufacturing and connected enterprise, ISA 95, Functional and physical subdivisions

UNIT - IV Predictive Maintenance 9 Hrs

Condition-based maintenance alerts: optimize machine availability, minimize interruption and increase throughput. **Analytics-** Descriptive: Pattern matching, Diagnostic: Classification, Predictive: Statistical methods and adaptive approach, Prescriptive: Optimization and simulation.

UNIT – V Inventory Optimization 9 Hrs

Supply chain inventory management: Newsboy, Base-stock, and (Q,r) models, multi-echelon supply chains, bullwhip effect. Performance modeling of supply chains using Markov chains and queueing networks. Mathematical programming models for supply chain planning, design, and optimization.

Total No of Hrs: 45

REFERENCE BOOKS

- 1.S. Jeschke, C. Brecher, H. Song, and D. B. Rawat, *Industrial Internet of Things: 2.Cybermanufacturing Systems*, Springer, 1st edition, 2017, ISBN: 978-3319425580.
3. T. Erl, Z. Mahmood, and R. Puttini, *Cloud Computing: Concepts, Technology & Architecture*, Prentice Hall, 1st edition, 2013, ISBN: 978-0133387520.
- 4.Sunil Chopra and Peter Meindel. *Supply Chain Management: Strategy, Planning, and Operation*, Prentice Hall of India, 2002.
- 5.Jeremy F. Shapiro. *Modeling the Supply Chain*.Duxbury Thomson Learning, 2001.
- 6.F. Cecelja, *Manufacturing Information and Data Systems*, 1st edition, Butterworth Heinemann, 2002, ISBN: 9781857180312
- 7.R. Zurawski, *Integration Technologies for Industrial Automated Systems*, 1st edition, CRC Press, 2006, ISBN: 9780849392627.